- The prerequisite is apparently CS 1331.
- This will be changed to CS 3510, and my recommendation is to wait until you've had this class.
- Informally: probability, algorithms, programming
- If you don't have sufficient preparation, there's only so much we can do to help you...

Pang and Lee define sentiment analysis broadly:

- Making a decision for a particular document
  - "is it positive or negative?"
  - "how positive is it?"
- Ordering a set of of texts
  - "rank these reviews by how positive they are"
- Giving a single label to an entire collection
  - "where on the scale between liberal and conservative do the writings of this author lie?"

- Categorizing the relationship between two enti- ties based on textual evidence
  - "does A approve of Bs actions?"

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NWS Atlanta @NWSAtlanta 19h · · · · More RT @LoznickaCBS46: Ugly skies over Buford, GA at this moment. Sent in from CBS46 viewer. cc: @NWSAtlanta #Atlanta pic.twitter.com/uzy2LUZnrC

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# Spam detection

# spam/

noun

- irrelevant or inappropriate messages sent on the Internet to a large number of recipients.
- trademark
   a canned meat product made mainly from ham.

verb

1. send the same message indiscriminately to (large numbers of recipients) on the Internet.





## Language classification





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Aleksi Kokkonen @Kokkis_+4h++++ More Hyvää huomenta kaikki!			
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# The bag-of-words representation



Darin [ATL Urbanist] @atlurbanist -11h Great sunset tonight, behind the clouds in Downtown Atlanta #atlanta #sunset #weloveatl pic.twitter.com/JsMZBIIIqw

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View photo

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#### $w_1 = \{ {\rm great}, {\rm sunset}, {\rm tonight}, \ldots \}$

 $w_2 = \! \{ \mathrm{ugly}, \mathrm{skies}, \mathrm{buford}, \ldots \}$ 

# The bag-of-words representation



Darin [ATL Urbanist] @atlurbanist - IIh Great sunset tonight, behind the clouds in Downtown Atlanta #atlanta #sunset #weloveatl pic.twitter.com/JsMZBIIlqw

**t3** 2 🗙 3

View photo

$$\mathbf{w}_1 = \{\text{great}, \text{sunset}, \text{tonight}, \ldots\}$$

 $w_2 = \{ \mathrm{ugly}, \mathrm{skies}, \mathrm{buford}, \ldots \}$ 

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# The bag-of-words representation



Darin [ATL Urbanist] @atlurbanist -11h Great sunset tonight, behind the clouds in Downtown Atlanta #atlanta #sunset #weloveatl pic.twitter.com/JsMZBlilgw

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View photo

$$\mathbf{w}_1 = \{\text{great}, \text{sunset}, \text{tonight}, \ldots\}$$

 $w_2 = \{ \mathrm{ugly}, \mathrm{skies}, \mathrm{buford}, \ldots \}$ 



$$\begin{aligned} & \textbf{x}_1 = \{ \mathrm{great}: 1, \mathrm{sunset}: 1, \mathrm{tonight}: 1, \ldots \} \\ & \textbf{x}_2 = \{ \mathrm{ugly}: 1, \mathrm{skies}: 1, \mathrm{buford}: 1, \ldots \} \end{aligned}$$

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Suppose  $y \in \mathcal{Y} = \{ pos, neg \}$ . Then,

$$\begin{aligned} \mathbf{f}(\mathbf{x}, y = \text{pos}) = & [\mathbf{x}^{\mathsf{T}}, \mathbf{0}^{\mathsf{T}} \\ \mathbf{f}(\mathbf{x}, y = \text{neg}) = & [\mathbf{0}^{\mathsf{T}}, \mathbf{x}^{\mathsf{T}} \\ \end{aligned} \end{bmatrix}^{\mathsf{T}}$$

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Suppose  $y \in \mathcal{Y} = \{pos, neg, neut\}$ . Then,

$$\begin{aligned} \mathbf{f}(\mathbf{x}, y = \text{pos}) = & [\mathbf{x}^{\mathsf{T}}, \mathbf{0}^{\mathsf{T}}, \mathbf{0}^{\mathsf{T}} ]^{\mathsf{T}} \\ \mathbf{f}(\mathbf{x}, y = \text{neg}) = & [\mathbf{0}^{\mathsf{T}}, \mathbf{x}^{\mathsf{T}}, \mathbf{0}^{\mathsf{T}} ]^{\mathsf{T}} \\ \mathbf{f}(\mathbf{x}, y = \text{neut}) = & [\mathbf{0}^{\mathsf{T}}, \mathbf{0}^{\mathsf{T}}, \mathbf{x}^{\mathsf{T}} ]^{\mathsf{T}} \end{aligned}$$

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The feature vector is composed of individual feature functions, e.g.:

$$f_{176}(\mathbf{x}, y) := x_{176} \times \delta(y = \mathsf{pos})$$
$$= \delta(\mathsf{great} \in \mathbf{w} \land y = \mathsf{pos})$$
$$f_{177}(\mathbf{x}, y) := x_{177} \times \delta(y = \mathsf{pos})$$
$$f_{10176}(\mathbf{x}, y) := x_{176} \times \delta(y = \mathsf{neg}) \dots$$

Suppose  $y \in \mathcal{Y} = \{\text{pos}, \text{neg}, \text{neut}\}$ . Then,

$$\begin{aligned} \mathbf{f}(\mathbf{x}, y = \text{pos}) = & [\mathbf{x}^{\mathsf{T}}, \mathbf{0}^{\mathsf{T}}, \mathbf{0}^{\mathsf{T}}, 1]^{\mathsf{T}} \\ \mathbf{f}(\mathbf{x}, y = \text{neg}) = & [\mathbf{0}^{\mathsf{T}}, \mathbf{x}^{\mathsf{T}}, \mathbf{0}^{\mathsf{T}}, 1]^{\mathsf{T}} \\ \mathbf{f}(\mathbf{x}, y = \text{neut}) = & [\mathbf{0}^{\mathsf{T}}, \mathbf{0}^{\mathsf{T}}, \mathbf{x}^{\mathsf{T}}, 1]^{\mathsf{T}} \end{aligned}$$

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$$= \delta(\text{great} \in \mathbf{w} \land y = \mathsf{pos})$$
$$f_{177}(\mathbf{x}, y) := x_{177} \times \delta(y = \mathsf{pos})$$
$$f_{10176}(\mathbf{x}, y) := x_{176} \times \delta(y = \mathsf{neg}) \dots$$

We usually add an "offset" feature at the end of each vector.

## Prediction by addition

• We can then define **weights** for each feature:

$$\begin{split} \langle \mathrm{great}, \mathsf{pos} \rangle &= 1, \langle \mathrm{great}, \mathsf{neg} \rangle = -1, \langle \mathrm{great}, \mathsf{neut} \rangle = 0, \\ \langle \mathrm{ugly}, \mathsf{pos} \rangle &= -1, \langle \mathrm{ugly}, \mathsf{neg} \rangle = 1, \langle \mathrm{ugly}, \mathsf{neut} \rangle = 0, \\ \langle \mathrm{buford}, \mathsf{pos} \rangle &= 0, \langle \mathrm{buford}, \mathsf{neg} \rangle = 0, \langle \mathrm{buford}, \mathsf{neut} \rangle = 0, \\ \dots \end{split}$$

#### Prediction by addition

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$$\begin{split} \boldsymbol{\theta} &= \{ \langle \mathrm{great}, \mathsf{pos} \rangle = 1, \langle \mathrm{great}, \mathsf{neg} \rangle = -1, \langle \mathrm{great}, \mathsf{neut} \rangle = 0, \\ \langle \mathrm{ugly}, \mathsf{pos} \rangle = -1, \langle \mathrm{ugly}, \mathsf{neg} \rangle = 1, \langle \mathrm{ugly}, \mathsf{neut} \rangle = 0, \\ \langle \mathrm{buford}, \mathsf{pos} \rangle = 0, \langle \mathrm{buford}, \mathsf{neg} \rangle = 0, \langle \mathrm{buford}, \mathsf{neut} \rangle = 0, \\ \dots \} \end{split}$$

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- We can arrange these weights into a vector.
- The score for any instance and label is equal to the sum of the weights for all features in the instance:

$$\psi_{y,\mathbf{x}} = \sum_{n} \theta_{n} f_{n}(\mathbf{x}, y)$$
$$= \theta^{\mathsf{T}} \mathbf{f}(\mathbf{x}, y)$$
$$\hat{y} = \arg \max_{y} \theta^{\mathsf{T}} \mathbf{f}(\mathbf{x}, y)$$

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• Set them by hand

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- Set them by hand
- Probability

- Set them by hand
- Probability
- Discriminative learning

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- Set them by hand
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